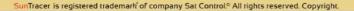
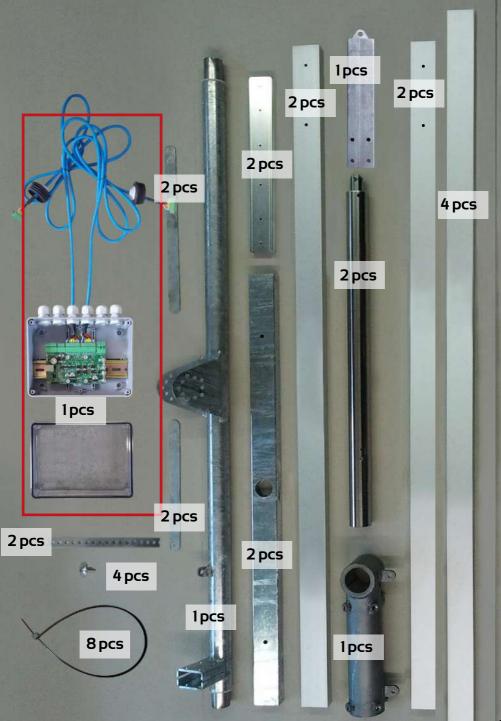
INSTRUCTIONS FOR INSTALATION AND USE

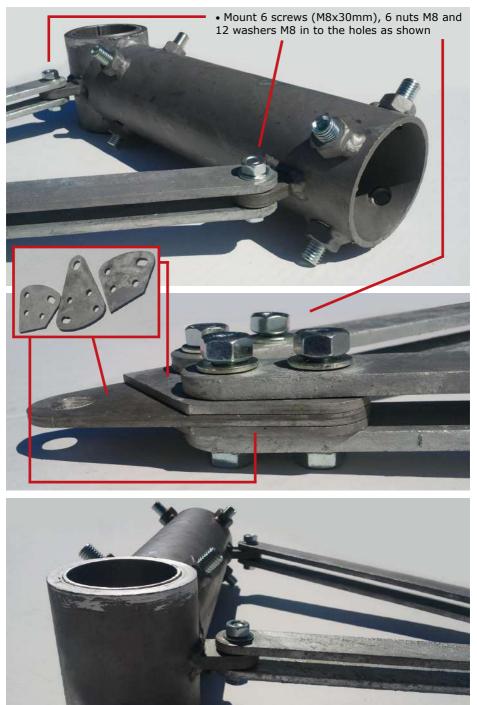
ST44M2V4P - a dual axis sun tracker



0 0	8 pcs	9	5 pcs M8 x 110mm
0	2pcs	9	4 pcs M8 x 80mm
0		(4 pcs M8 x 50mm
	16 pcs	0	2 pcs M12 x 90mm
The second		d 	6 pcs M8 x 30mm
		<u>)</u>	1 pcs M10 x 50mm
	4 pcs	0000	8 pcs M8 x 16mm
And a second sec		800	24 pcs M6 x 12mm
	2 pcs	-	8 pcs M12 x 20mm
		0	4 pcs M8 x 40mm
	lpcs	0	4 pcs M8 x 30mm
C	2pcs	0	4 pcs M12
Comment		0	46 pcs M8
	1pcs	۲	2 pcs M12
3)=	1pcs	ଭ	45 pcs M8
1	8 pcs	C	3 pcs Ø7mm

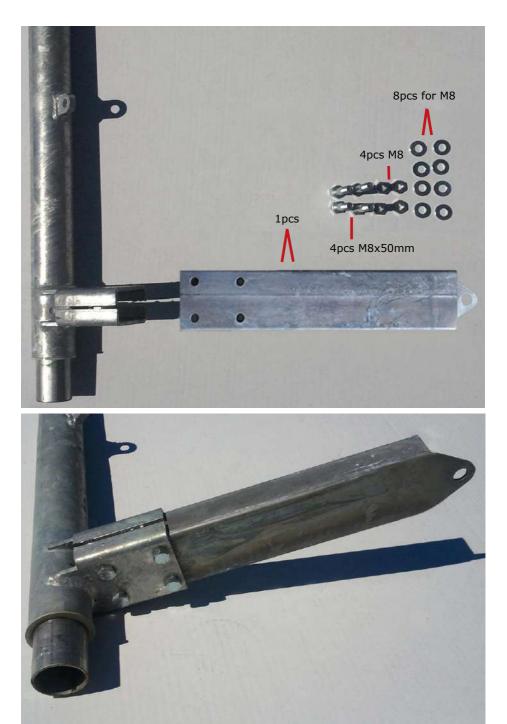






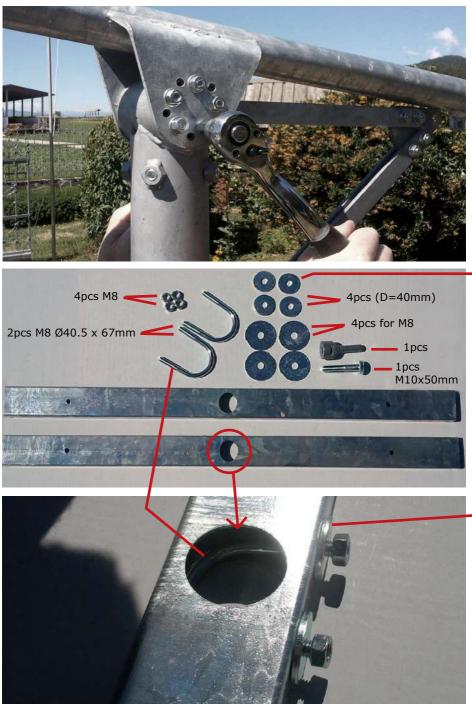


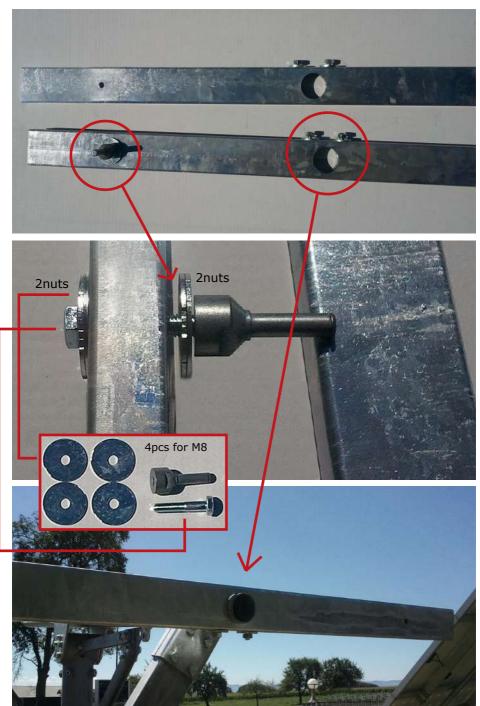
• Before you tighten screws, align vertical axis from the EAST-WEST side and the NORTH-SOUTH as shown in the figure

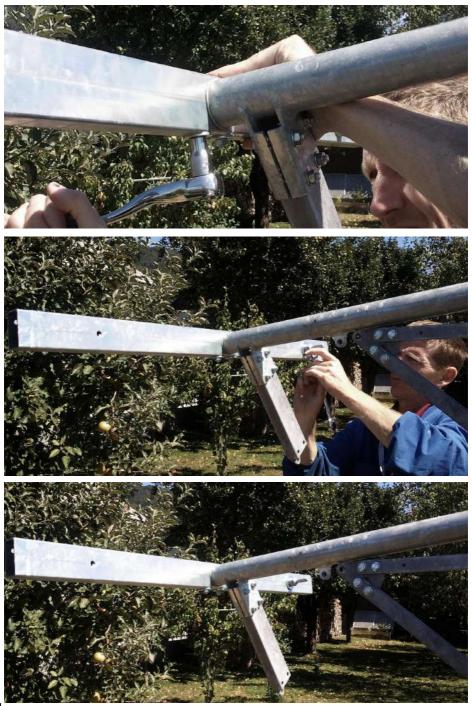




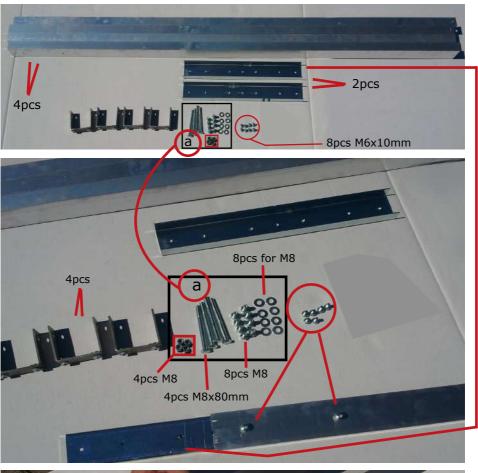


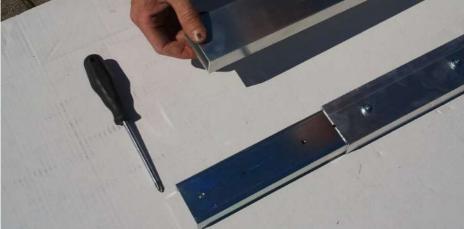


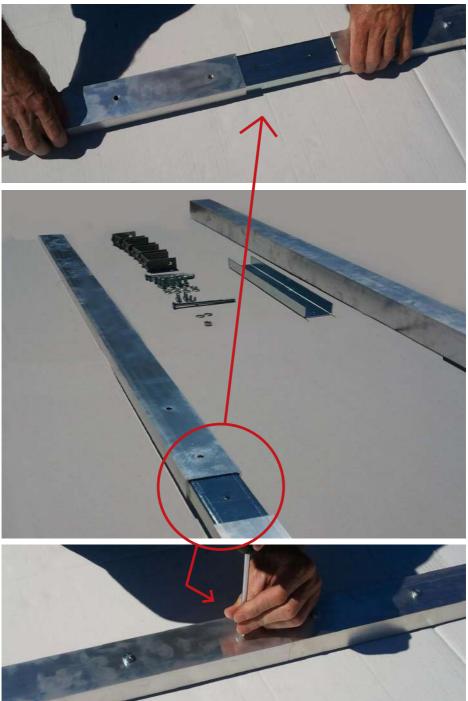


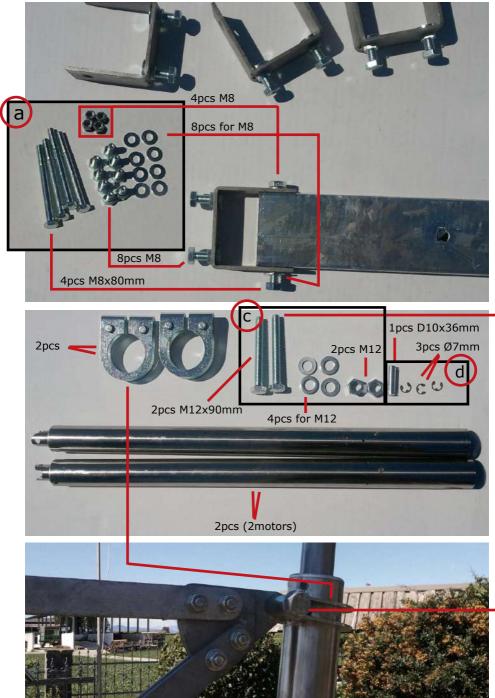


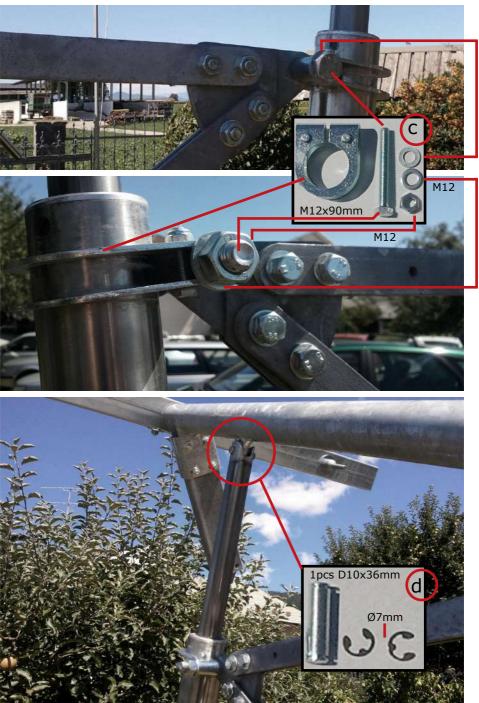


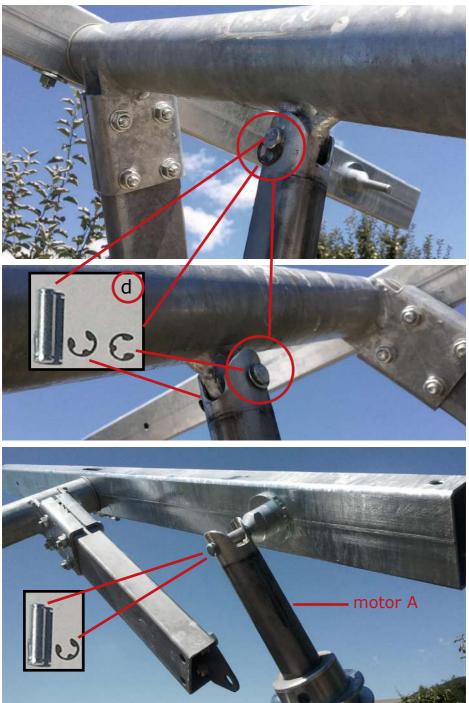


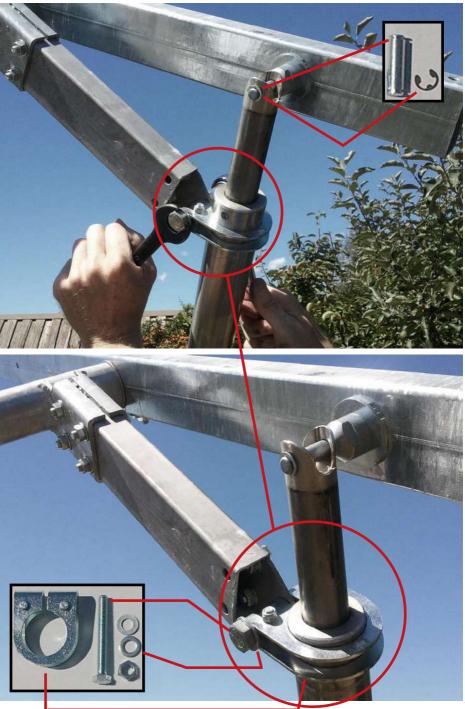








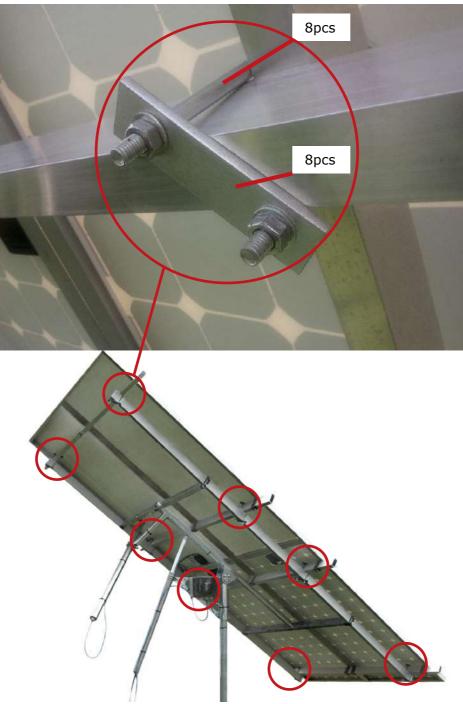


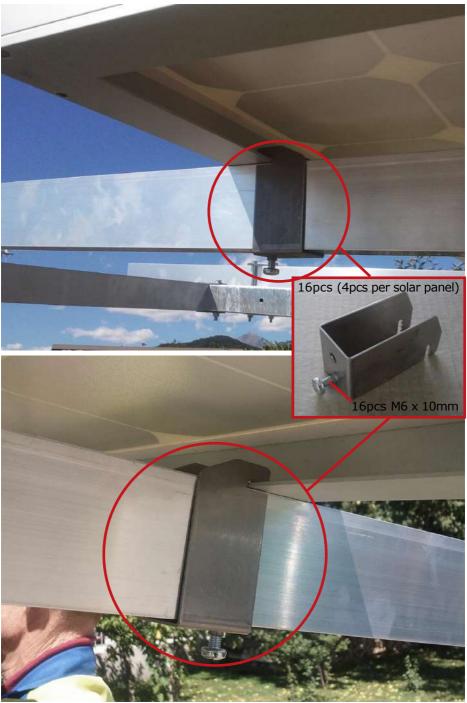














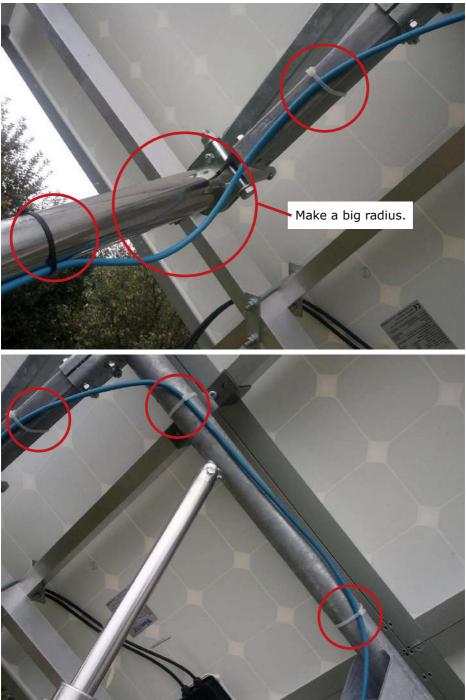




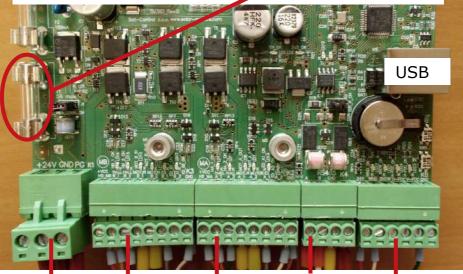








Before wiring junction box, take out the transparent fuse so indicator on connection board turns off.



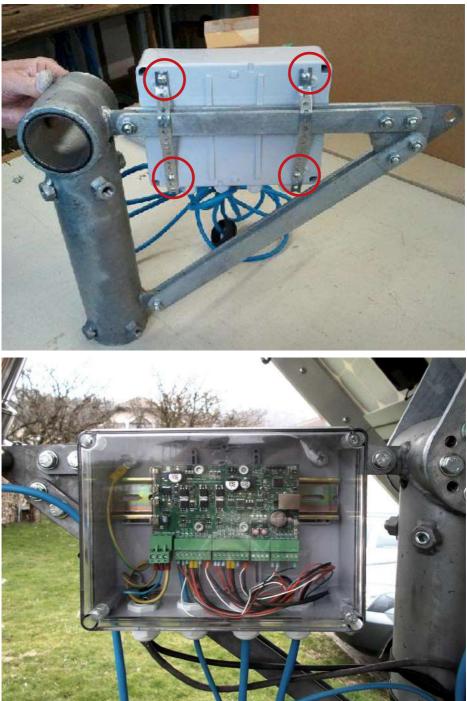
power supply motor B

motor A

RS485 wind sensor & optionally optical sensor



Before you connect power system be aware of plus and minus in a right terminal. Connect one wire into the plus and the other one into the minus!



FIRST CONNECTION OF TRACKER TO A PC OVER AN USB CONNECTION DRIVER INSTALLING

• Connect your PC to the tracker using the enclosed communication cable. Use the USB port on your computer.



• Computer will require its driver installation. Let windows choose your driver automatically. When the driver is not found install latest custom windows updates.



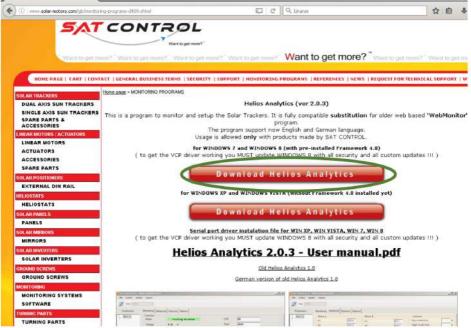
• When the next window appear, click on "No, not this time" and than Install the software automatically .

HOW TO SETUP HELIOS ANALYTICS

STEP-BY-STEP INSTRUCTIONS:

1. DownloadHelios analytics from www.solar-motors.com to C:\Users\USER\Downloads





- 2. Extract downloaded file to disk C:\Program Files (x86)\HELIOS
- 3. Runor openHeliosAnalytics.exe from the folder where all other original files and folders are. If you want to run from desktop, make shortcut on desktop! Do not copy this file on desktop, because will not work!

C0146	Mode	Link	
	Voltage: V	Туре:	
	Sunrise:	Version;	
	Sunset:	Service.	
	System settings	Tracker control	Motor A
	Solar h/m/s	Enable	Angle:
	Solar d/m/y.	Automatic tracking: Disable	Position:
	GMT h/m/s:		Destination:
	GMT d/m/y: /	H/V Alignment Snow	I motor.
	Time zone: h	Wind Custom	100 CO 100
	Lon/Lat:		Status:
	Moving interval s	Do reference A Do reference B	Error.
	Sync time		
	Common		Motor B
	Power failed Button pressed	Automatic tracking must be disabled!	Angle
	F Button stuck		Position
	A end switch pressed		Destination:
	B end switch pressed A loosing hall pulses		I motor:
	E loosing hall pulses		Status:
	A&B async Low sun radioation/ Stop&Clear	Stop motors	
	Snow input/ Reference input(6)	Clear	Error
			c
	1		
	E Vrata (COI		
		unications Port (COM1) Irallel Port (LPT3)	

 Choose right COM port.You can check which COM port in ->START -> COMPUTER -> PROPERTIES -> DEVICE MANAGER -> PORTS COM & LPT -> check for STMicroelectronics Virtual COM port (COMx) (x is a number).

In our case, we choose COM6 and	nress connect	(the hutton left	heside COM r	orts

File	System	Update	Support		
-	Port:	DM6	*		
P	ositioners		Monitoring	Advanced	Sen
1 0	6A1(1)		Overview		

5. The numbers appear and link is counting; now disabletracking in case tracking enabled.

36A1(1)	Overview			
	Mode:	tracking	ok	Link:
	Voltage:	3.78 V		Туре:
	Sunrise:	05:59:40 (Local	:06:42:04)	Version
	Sunset:	18:15:22 (Local	:18:57:46)	Service
	System settings		Tracker control	
	Solar h/m/s:	18 : 17 : 23	Automatic tracking:	Enable
	Solar d/m/y:	21 / 03 / 2016	Automatic tracking.	Disable

6. Click "Do reference A" and confirm action to initiate a position calibrating for motor A. When motor A stops, click "Do reference B" and confirm action to initiate a position calibrating for motor B

WARNING : Before proceeding to this step, make sure that all connectors are plugged in all wires and screws are properly tied in junction box and on motor's side! If not, all further actions can lead to serious damage of tracker! The power 24VDC must be on!

(() () () () () () () () () (
Positioners	Monitoring Advance	ed Sensors Options	1	
36A1(1)	Overview Mode:	tracking dis	abled	Link:
	Voltage:	3.87 V		Type:
	Sunrise:	Sunrise: 05: 59:40 (Local:06:42:04)		Version:
	Sunset:	18:15:22 (Local:	18:57:46)	Service:
	System settings		Tracker control	
	Solar h/m/s:	20 30 06	A down to A south the	Enable
	Solar d/m/y:	21 / 03 / 2016	Automatic tracking	Disable
	GMT h/m/s:	20 12 29		
	GMT d/m/y:	21 / 03 / 2016	H/V Alignment	Snow
	Time zone:	1.0 h	Wind	Custom
	Lon/Lat:	4.4000 * 51.4000 *		
	Moving interval:	300 s	Do reference A	Do reference B



Click "Do reference A" and confirm action. When motor A stops, click "Do reference B". You can proceed when motor stops moving and both positions are same as parameter "min range A" and "min range B" under tab Advanced parameters. Important Note: The motor fully retracts then goes to "min range A/B". Check whether motor position is "0" (or "min range A/B" in case it is different from 0) when motor stops. In case it is not, please contact us. For additional information, refer to Helios Analytics manual.

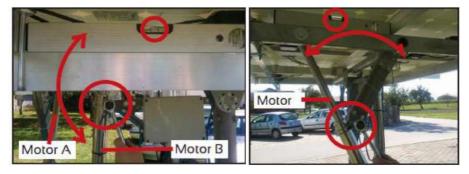
7. Sync time, set Longitude and atitude and time zone of yours's solar tracker position. (minus sign is WEST)

Port: COM6			
Positioners	Monitoring Advanced	Sensors Options	
36A1(1)	Overview Mode:	tracking disabled	Link:
	Voltage:	3.87 V	Type:
	Sunrise:	05:59:40 (Local:06:42:04)	Version
	Sunset:	18:15:22 (Local:18:57:46)	Service
	System settings	Tracker control	
		20 : 30 : 06	Enable
	Solar d/m/y:	Automatic tracking	Disable
	10.000/05/000000000000000000000000000000	20 : 12 : 29	
		21 / 03 / 2016 H/V Alignment	Snow
	and the second sec	1.0 h 4.4000 °51.4000 Wind	Custom
		4.4000 p1.4000	
	Sync time	Do reference A	De reference P

8. After the calibration is finished and motors stops, press H/V alignmento initiate horizontal alignment After motors stops, make mechanical calibration so, that you loosen the clamp of stator part of linear motor; adjust plate with solar panels fully horizontally with help of spirit level, then tight clamp back. Do it so by both linear motors. WARNING : At the time of horizontal alignment, check if parameter Min. range A is zero and parameter Min. range B is zero in Advanced tab. When are not zero, then set it to zero (both).

Port: CORIS	*			
Positioners	Monitoring Advance	ed Sensors Options		
36A1(1)	Overview Mode:	tracking disab	led	Link:
	Voltage:	3.87 V		Type:
	Sunrise:	05:59:40 (Local:06	5: 42: 04)	Version:
	Sunset:	18:15:22 (Local:18	3: 57: 46)	Service:
	System settings		Tracker control	
	Solar h/m/s:	20 30 06		Enable
	Solar d/m/y:	21 / 03 / 2016	Automatic tracking	Disable
	GMT h/m/s: GMT d/m/y:	20 12 29		0-000/04/11
	Time zone	1.0 h	H/V Alignment	Snow
	Lon/Lat	4.4000 * 51.4000 *	Wind	Custom
	Moving interval:	300 s		
	Sync time	1	Do reference A	Do reference B

See photos of horizontal aligning.



9. Enable tracking

Sat Control d.o.o -	Helios Analytics 2.0.3		
Preside and	date Support		
Port: COME Positioners	Monitoring Advanced Sensors C	Options	
] 36A1(1)	Voltage: 3.83 v Sunrise: 05:59:40 (ng disabled Local:06:42:04) Local:18:57:46)	Link: Type Version: Senice:
	System settings Solar h/m/s 13 02 49 Solar d/m/y 21 / 03 / 201 GMT h/m/s 12 45 13	6 Automatic tracking	Enable
	GMT d/m/y: 21 / 03 / 20 Time zone: 1.0 h Lon/Lat: 4.000 ° 51	6 H// Alignment	Do you want SunTracer to run automatically?
	Moving interval: 300 s	Do reference A	Do Confirm Prekliči

Start to use the Helios analytics and discover the advantages and benefits with help of user manual for Helios analytics.

Port: COM6	-				
Positioners	Monitoring Advanced Sensors C)ptions			
36A1(1)	Voltage: 3.83 v Sunrise: 05:59:40 (cking ok (Local:06:42:04) Local:18:57:46)	Link: Type: Version: Service:	80 36A1 6.63 (B1) Run:normal.Wi-0	
- Syste Solar GMT GMT Time Lon/L Movin	System settings Solar lv/m/s: 13 06 02 Solar d/m/y: 21 /03 /201 GMT lv/m/s: 12 48 26 GMT d/m/y: 21 /03 /201 Time zone: 1.0 h Lon/Lat: 4.4000 *[51: Moving interval: 300 s \$ \$ \$	16 Automatic tracking: 16 H/V Alignment	Enable Disable Snow Custom Do reference B	Error:	-46.2 18734 18734 0.00 dle
	Common Power failed Button pressed Button stuck A end switch pressed B end switch pressed Aloosing hall pulses B loosing hall pulses A&B sync Low sun radioation/ Stop&Cleat Snow input/ Reference input(6)		st be disabled	Error.	86.4 17605 17605 0.00

DECLARATION OF CONFORMITY according to ISO/IEC Guide 22 and EN 45014

Company/Manufacturer's Name: Sat Control d.o.o.

Address: Poženik 10, SI-4207 Cerklje, Slovenia / EU

declares under its sole responsibility, that the product

Product name: Solar Tracker

Model number: ST44M2V4P, ST44M2V3P, ST44M2V2P, ST40M2V3P, ST40M2V2P

Product options: (+) All

conforms to the following directives and/or standards

- EN 55013 :97 +A12 :97 +A13 :97 +A14 :00
- EN 55020 :95 +A11 :97 +A12 :00 +A13 :00 +A14 :00
- EN61000-3-3 :97
- SIST EN 61000-3-2 :97 +A1 :99 +A2 :00
- IEC 60065 :98

Supplementary Information:

The product herewith complies with the requirements of the following Directives and carries the CE-marking accordingly:

- the Electromagnetic compatibility (EMC) directive 89/336/EEC
- Low voltage equipment directive 73/23/EEC



Place and date of issue

(name, function) (signature, stamp)

Cerklje, 1st June 2010



Sat Control d.o.o., Poženik 10, 4207 Cerklje, SLOVENIA Phone: +386 4 281 62 00, Fax. +386 4 281 62 13, www.solar-motors.com, info@solar-motors.com